GlobSol Overview

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• This is a modification of a talk given at COCOS’02.
• Only overall aspects are discussed.
• Talk with me for details concerning the underlying algorithms.
Interval Global Optimization: Goals

Given a box

$$\mathbf{x} = ([x_1, \overline{x}_1], \ldots [x_n, \overline{x}_n]),$$

find small boxes

$$\mathbf{x}^* = ([x_1^*, \overline{x}_1^*], \ldots [x_n^*, \overline{x}_n^*])$$

such that any solutions of

minimize $\phi(x)$

subject to $c_i(x) = 0, i = 1, \ldots, m_1,$

$g_i(x) \leq 0, i = 1, \ldots, m_2,$

where $\phi : \mathbb{R}^n \rightarrow \mathbb{R}$ and $c_i, g_i : \mathbb{R}^n \rightarrow \mathbb{R}$

are guaranteed to be within one of the $\mathbf{x}^*$ that has been found.
Elements of GlobSol

• automatic differentiation,
• constraint propagation,
• interval Newton methods,
• additional, specialized techniques.
Automatic Differentiation in GlobSol

• Designed originally for small problems.
• Implemented simply, to aid understanding of the code and minimize implementation effort.
• Serves its purpose, but certain inefficiencies are present.
Predecessors and History

GlobSol began as a research test bed, and grew out of the following earlier packages.

**INTBIS:** A FORTRAN-77 package for verified solution of nonlinear algebraic systems (ACM TOMS Algorithm 681, 1990)

**INTLIB:** A FORTRAN-77 library for interval evaluation of standard functions (ACM TOMS Algorithm 737, 1994) 47 (2) (1991), pp. 169–191

**INTERVAL ARITHMETIC:** A Fortran-90 module providing an interval data type and an interface to **INTLIB** (ACM TOMS Algorithm 763, 1996).
Predecessors and History

(continued)

AD, algorithm improvements:

The Sun Microsystems project: User interface, testing and bug removal, improvements, applications; first called “GlobSol”

http://www.mscs.mu.edu/~globsol/
INTBIS and INTLIB

- Emphasis is on simplicity and ability of user to modify the code and to port the code.
- There is no constraint propagation other than interval Newton methods, and algorithms are simple.
- Except for polynomial systems, the user inputs the equations by assembly-language-like programming.

Nonetheless:

- Evaluation of the equations (constraints) is significantly more efficient than in GlobSol.
- Stadtherr et al have modified INTBIS / INTLIB for some of the most impressive application successes in the field.
The GlobSol Script

globsol <source file> <data number>

1. Compiles and runs the user-provided Fortran-90 program to produce the internal representation, or codelist for the objective, constraints, and gradients.

2. Runs an optimizing program that removes redundant operations from the code list.

3. Runs the overall GlobSol optimization process.

4. Cleans the directory and temporary files.
GlobSol’s Global Search Routine
rigorous_global_search.f90

1. Remove a box \( \mathbf{x} \) from a list of not-yet-examined boxes \( \mathcal{L} \).

2. *IF* \( \mathbf{x} \) is sufficiently small *THEN* store \( \mathbf{x} \) and *CYCLE*.

3. Use constraint propagation to possibly narrow the coordinate widths of the box \( \mathbf{x} \) and possibly reject the box \( \mathbf{x} \).

4. Perform an interval Newton method to possibly narrow the coordinate widths of \( \mathbf{x} \) and to possibly reject \( \mathbf{x} \).

5. *IF* the coordinate widths of \( \mathbf{x} \) are now sufficiently narrow *THEN* store \( \mathbf{x} \) and *CYCLE*.

6. (Subdivide) Bisect \( \mathbf{x} \) along a chosen coordinate, forming two new boxes; place these boxes on the list \( \mathcal{L} \).
Use of GlobSol: Required Files

(How the user controls GlobSol)

**GlobSol.CFG:** The GlobSol configuration file. This is used to
- control printing,
- set tolerances,
- select algorithm components, such as choice of preconditioner, choice of interval Newton method, form of problem (nonlinear system optimization), etc.

*<name>*.f90: The user-supplied Fortran 90 source file defining the objective and constraints.

*<name>*.DT#: The “box data file.” where the user supplies search limits, which coordinates are considered as bound constraints, and an initial guess for a global optimizer, if available.
The Configuration File
GlobSol.CFG

• Is largely self-documenting.

• Users should seldom need to change items other than level of printing, tolerances, and type of problem, and things such as the total CPU time to be allowed to solve a particular problem.

• GlobSol contains several algorithm variants of an experimental nature. Some variants are not presently supported at the level that more promising variants are; users should be wary of changing the configuration file to use these variants.
An Example Problem and Box Data file

minimize \( \phi(X) = -2 * x_1^2 - x_2^2 \)
subject to constraints
\[
\begin{align*}
x_1^2 + x_2^2 - 1 & \leq 0 \\
x_1^2 - x_2 & \leq 0 \\
x_1^2 - x_2^2 & = 0
\end{align*}
\]
mixed.DT1
1D-5 ! General domain tolerance
0 1 ! Bounds on the first variable
0 1 ! Bounds on the second variable
F F ! X(1) has no bound constraints
F F ! X(2) has no bound constraints

Subsequent optional lines can give an initial guess point.
A Simple User-Supplied Function file mixed.f90

PROGRAM SIMPLE_MIXED_CONSTRAINTS
  USE CODELIST_CREATION
  PARAMETER (NN = 2)
  TYPE(CDLVAR), DIMENSION(NN) :: X
  TYPE(CDLLHS), DIMENSION(1) :: PHI
  TYPE(CDLINEQ), DIMENSION(2) :: G
  TYPE(CDLEQ), DIMENSION(1) :: C

  CALL INITIALIZE_CODELIST(X)

  PHI(1) = -2*X(1)**2 - X(2)**2
  G(1) = X(1)**2 + X(2)**2 - 1
  G(2) = X(1)**2 - X(2)
  C(1) = X(1)**2 - X(2)**2

  CALL FINISH_CODELIST
END PROGRAM SIMPLE_MIXED_CONSTRAINTS

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Typing "globsol mixed 1" gives \texttt{mixed.OT1}, containing:

Output from FIND\_GLOBAL\_MIN on 04/06/1999 at 08:03:52.
Version for the system is: March 20, 1999

Codelist file name is: MIXEDG.CDL
Box data file name is: MIXED.DT1

Initial box:
\[ [ 0.0000E+00, 0.1000E+01 ] [ 0.0000E+00, 0.1000E+01 ] \]

\texttt{BOUND\_CONSTRAINT:}
\begin{verbatim}
  F F F F
\end{verbatim}

\begin{verbatim}
CONFIGURATION VALUES:
EPS\_DOMAIN: 0.1000E-04 MAXITR: 60000
DO\_INTERVAL\_NEWTON: T QUADRATIC: T FULL\_SPACE: F
VERY\_GOOD\_INITIAL\_GUESS:F
USE\_SUBSIT:T
OUTPUT UNIT:7 PRINT\_LENGTH:1
\end{verbatim}
Default point optimizer was used.
Globsol Output File

abridged second part

THERE WERE NO BOXES IN COMPLETED_LIST.

LIST OF BOXES CONTAINING VERIFIED FEASIBLE POINTS:

Box no.: 1
Box coordinates:
[ 0.7071E+00, 0.7071E+00 ] [ 0.7071E+00, 0.7071E+00 ]
PHI:
[ -0.1500E+01, -0.1500E+01 ]
Level: 3
Box contains the following approximate root:
  0.7071E+00  0.7071E+00
OBJECTIVE ENCLOSURE AT APPROXIMATE ROOT:
[ -0.1500E+01, -0.1500E+01 ]
U0:
[ 0.3852E+00, 0.3852E+00 ]
U:
[ 0.5777E+00, 0.5777E+00 ] [ 0.0000E+00, 0.1000E+01 ]
V:
[ 0.1926E+00, 0.1926E+00 ]
INEQ_CERT_FEASIBLE:
  F  T
NIN_POSS_BINDING: 1

Number of bisections: 1
BEST_ESTIMATE: -0.1500E+01
Total number of boxes processed in loop: 4
Overall CPU time: 0.5000D-01

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Advice on GlobSol’s Use

*Interpretation of Results*

- The only guarantees (at present): Any global minimizers must lie within the boxes in the output list.
- A non-empty output list does not guarantee existence of global minima.
- An empty output list does not necessarily mean a bug. It usually means either an overconstrained or an underconstrained problem. (The search box does not correspond to bound constraints unless explicitly set.)
Advice on GlobSol’s Use

Turning On and Off Constraint Propagation

- On average, and for most problems, constraint propagation gives a small but significant improvement in GlobSol’s overall performance.
- Constraint propagation is indispensable for some problems.
- Because inverses are not implemented in extended arithmetic in GlobSol, constraint propagation does not work for some problems.
- Users can experiment with the switch USE_SUBSIT (use “substitution-iteration”) in GlobSol.CFG to turn on and off constraint propagation.
Advice on Bound Constraints

- GlobSol solves unconstrained problems more efficiently than constrained problems.
  - Large numbers of bound constraints lead to excessive “peeling.”
  - In practice, interval Newton methods do not seem to function well with the Fritz–John system for larger boxes.

- Suggestion:
  1. Start with an unconstrained system.
  2. Selectively add constraints until the problem has a solution.
  3. Experiment with which constraints are important.

But does this correspond to optimal use of constraint technology???
On Equality Constraints, Data Fitting

• We have tried GlobSol with numerous test sets with nonlinear least squares problems and nonlinear minimax problems (which we reformulated as smooth problems with constraints using Lemaréchal’s technique).

• GlobSol almost uniformly failed to solve these problems efficiently.

• Although the Fritz–John matrix is not necessarily singular at critical points, we believe the problems to be related to intrinsic properties of the Fritz–John matrix, in the case of minimax problems.

• We have also tried several variants for least squares, without success.

• Thus, GlobSol cannot presently handle overdetermined systems well.
Possibilities for Data Fitting Problems

• For the interval Newton method, reformulate the minimax problem as an uncertain linear programming problem, and solve with Jansson’s techniques.

• Reformulate as a system of equations with tolerances (as Hansen / Walster explain).
  – We have experimented in some depth with this technique last summer.
  – Although hopeful, we don’t have a final answer yet.
  – This technique will involve getting the user to accept a different interpretation of “solution”. The solution will not be least-squares or minimax, but a set over which all residuals are within a tolerance. (See my talk on the linear case from Validated Computing 2002.)
GlobSol’s Future

- Totally rewrite to simplify the structure more.
- Improve the user interface (better I/O) and low-level (more efficient code list interpretation, etc.)
- Include of additional good algorithms of others (the LP rejection technique of Nenov, van Hentenryck’s univariate search, etc.)
- Do additional research on new algorithms (such as for nonlinear data fitting).

These items need to be prioritized, and time resources need to be found.