

Numerical Analysis Comprehensive Examination

Tuesday, August 7, 2012, 9:00AM to 1:00PM, MDD 208

This exam is closed book, but calculators are permitted (and will be useful). Please use your own paper, and put your name on each sheet.

1. Consider

$$A = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{3} & \frac{1}{4} \\ \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \end{pmatrix}. \quad (1)$$

- Compute the condition number with respect to $\|\cdot\|_\infty$ of A .
- If one were computing the solution of $Ax = b$, with A as in (1), and one were using floating point arithmetic with 5 significant digits, how many digits would you expect would be correct in the computed solution for x ? (A formal proof is not needed — use the common rule of thumb.)

2. Assume that $f \in \mathcal{C}^2[a, b]$. Let $M = \max_{x \in [a, b]} |f''(x)|$.

(a) Prove that

$$\left| \int_a^b f(x) dx - (b-a) f\left(\frac{a+b}{2}\right) \right| \leq (b-a)^3 \frac{M}{24}.$$

(b) Prove that

$$\left| \int_a^b f(x) dx - \sum_{j=0}^{N-1} \frac{b-a}{N} f\left(\frac{a_j + a_{j+1}}{2}\right) \right| \leq \frac{(b-a)^3 M}{24N^2},$$

where $a_j = a + (j-1)h$ with $h = (b-a)/N$.

3. Consider the iteration

$$x^{(k+1)} = Gx^{(k)} + q, \quad \text{where } G = \begin{pmatrix} 0 & 0 & 0 & 0 \\ -\frac{1}{4} & 0 & -\frac{1}{4} & 0 \\ 0 & -\frac{1}{4} & 0 & -\frac{1}{4} \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \text{and } q = \begin{pmatrix} \frac{1}{6}f_0 \\ \frac{1}{4}f_1 \\ \frac{1}{4}f_2 \\ \frac{1}{6}f_3 \end{pmatrix}. \quad (2)$$

- Prove that the iteration (2) has a fixed point x^* .
- Find the smallest constant $C > 0$ you can such that $\|x^{(k+1)} - x^*\|_1 \leq C \|x^{(k)} - x^*\|_1$.
- Prove that

$$\|x^{(k)} - x^*\| \leq \|G\|^k \|x^{(0)} - x^*\| \quad \text{and} \quad \|x^{(k)} - x^*\| \leq \frac{\|G\|^k}{(1 - \|G\|)} \|x^{(1)} - x^{(0)}\|$$

4. (Related to problem 3) Now consider the system

$$Ax = f, \quad \text{where } A = \begin{pmatrix} 6 & 0 & 0 & 0 \\ 1 & 4 & 1 & 0 \\ 0 & 1 & 4 & 1 \\ 0 & 0 & 0 & 6 \end{pmatrix} \quad \text{and } f = \begin{pmatrix} 0 \\ \sqrt{3}/2 \\ \sqrt{3}/2 \\ 0 \end{pmatrix}. \quad (3)$$

- Explain the relationship between (3) and the iteration (2).
- Solve the system (3) by hand. (You may do it numerically, carrying three significant figures.)
- Do two iterations of (2), starting with $x^{(0)} = q$. Compare what you get to the value C you obtained in 3b and to the approximate solution you obtained in the step previous to this one.

5. Consider approximating $f(x) = \cos(x) - 1$ in the interval $x \in [-0.1, 0.1]$ by a degree-2 polynomial.

- Write down the degree-2 Taylor polynomial, and give a bound on the error in $[-0.1, 0.1]$.
- Write down the degree 2 interpolating polynomial at the points $x_0 = -0.1$, $x_1 = 0$, and $x_2 = 0.1$, and give a bound for the error. Write the polynomial in power form so it can be compared to part (a).
- Write down the least-squares approximation to f by a polynomial of degree 2, with respect to the dot product

$$(f, g) = \int_{-0.1}^{0.1} f(x)g(x)dx.$$

- Compare the coefficients in (a), (b), and (c).
- For values of x very near zero, if you use floating point arithmetic, do you think it would be better to evaluate f using the system-provided cosine function or one of the quadratic approximants? Why?

6. Suppose $A = LU$, where

$$L = \begin{pmatrix} 1 & 0 & 0 & 0 \\ \frac{1}{6} & 1 & 0 & 0 \\ 0 & \frac{1}{4} & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{and } U = \begin{pmatrix} 6 & 0 & 0 & 0 \\ 0 & 4 & 1 & 0 \\ 0 & 0 & \frac{15}{4} & 1 \\ 0 & 0 & 0 & 6 \end{pmatrix}.$$

Compute the solution x to $Ax = b$, where $b = (0, 0.866, 0.866, 0)^T$, without first forming A . (You may use floating point approximations with 3 significant decimal digits, if you so desire.)

7. Consider the initial value problem

$$y'(t) = f(t, y), \quad y(t_0) = y_0, \quad (4)$$

and consider the implicit solution method

$$t_{k+1} = t_k + h, \quad y^{(k+1)} = y^{(k)} + \frac{h}{2} (f^{(k)} + f^{(k+1)}), \quad (5)$$

where $f^{(k)} = f(t_k, y_k)$ and y_k is the approximation given by the method to $y(t_k)$.

- (a) What is the order of this method? Why?
- (b) Compute the region of stability in the complex plane of this method.

8. Do three steps of Newton's method,

- (a) on the equation $f(z) = z^2 + 1$, $z^{(0)} = 0.2 + 0.8i$, and
- (b) on the system of equations

$$F(x, y) = \begin{pmatrix} x^2 - y^2 + 1 \\ 2xy \end{pmatrix},$$

with starting vector $x^{(0)} = (0.2, 0.8)^T$.

- (c) Compare the results of your last two computations. What do you find? Why?

9. Using Taylor's formula, find an expression for the discretization error in approximating $f'(x_0)$ by the formula

$$f'(x_0) \approx \frac{1}{2h} \{-3f(x_0) + f(x_0 + h) - f(x_0 + 2h)\}.$$