TECHNICAL MEMORANDUM: MATHEMATICS

INTERVAL INTEGRALS

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Lockheed

MISSILES and SPACE DIVISION LOCKHEED AIRCRAFT CORPORATION - SUNNYVALE, CALIF.

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TECHNICAL MEMORANDUM: MATHEMATICS

INTERVAL INTEGRALS

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FOREWORD

This report presents results obtained in connection with research on automatic error analysis.

ABSTRACT

An arithmetic for intervals was studied by Moore and Yang (Ref. 1) as a basis for error analysis in digital computations. In that study, an integral $\int_A F$ was defined for certain functions F whose domain and range are contained in the space of bounded closed intervals of real numbers. The present paper establishes further properties of the integral defined there and relates this integral to integration of ordinary real-valued functions.

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Section 1 INTRODUCTION

R will be used to denote the real line. Whenever a and b are real numbers with $a \le b$, [a,b] will denote the subset of R consisting of all real numbers x such that $a \le x \le b$. By $\mathcal J$ we will denote the set of all intervals [a,b] contained in some interval. (Most of our results hold for $\widetilde{\mathcal J} = \{[a,b] \mid a \in R \text{ and } b \in R\}$. (Arguments involving compactness and uniform continuity lead us to work in $\mathcal J$.) We use the usual metric topology in $\mathcal J$. $\mathcal S = \mathcal S$ will denote a subdivision of [a,b];

$$S = \{a = x_0, x_1, x_2, \dots, x_{n-1}, x_n = b\}$$

When the points of the subdivision are equally spaced, it will sometimes be denoted by \mathcal{S}_n . By [a,b] r, where r is a real number, we mean the set of all xr such that $x \in [a,b]$. We denote by $\Sigma(F,\mathcal{S})$ the summation

$$\Sigma(\mathbf{F}, \mathcal{S}) = \mathbf{F} \begin{bmatrix} \mathbf{x}_0, \mathbf{x}_1 \end{bmatrix} (\mathbf{x}_1 - \mathbf{x}_0) + \mathbf{F} \begin{bmatrix} \mathbf{x}_1, \mathbf{x}_2 \end{bmatrix} (\mathbf{x}_2 - \mathbf{x}_1) + \cdots$$

$$+ \mathbf{F} \begin{bmatrix} \mathbf{x}_{n-1}, \mathbf{x}_n \end{bmatrix} (\mathbf{x}_n - \mathbf{x}_{n-1})$$

Then Moore and Yang's integral is defined for each continuous function $F: \mathcal{J} \to \mathcal{J}$ for which $F(A) \subset F(B)$ whenever A is an interval contained in the interval B, by

$$\int_{[a,b]} F = \bigcap_{S} \{\Sigma(F,S)\}$$

Section 2 CONTINUITY OF INTEGRATION

Theorem 1. Let $F: \mathcal{J} \to \mathcal{J}$ be a continuous function such that $A \subset B \Rightarrow F(A) \subset F(B)$. Define $G: \mathcal{J} \to \mathcal{J}$ by $G \left[a, b\right] = \int F$. Then G is continuous.

Proof: Consider

$$G\left[a_{o}^{\dagger},b_{o}^{\dagger}\right] = \int_{\left[a_{o}^{\dagger},b_{o}^{\dagger}\right]} F = \int_{\left[a_{o}^{\dagger},b_{o}^{\dagger}\right]} \left\{\Sigma\left(F,\mathcal{S}_{\left[a_{o}^{\dagger},b_{o}^{\dagger}\right]}\right)\right\},$$

$$\epsilon > 0, G\left[a_{o}^{\dagger},b_{o}^{\dagger}\right] \epsilon V_{\epsilon}$$

where V_{ϵ} = the open interval beginning at the left end-point of $G\left[a_{o}^{},b_{o}^{}\right]$ minus ϵ and ending at the right end-point plus ϵ . The term $G\left[a_{o}^{},b_{o}^{}\right]$ is an interval properly contained in V_{ϵ} and is the intersection of intervals I_{α} ; therefore, one of these intervals I_{1} has a right end-point less than the right end-point of $G\left[a_{o}^{},b_{o}^{}\right]+\epsilon/2$. Similarly, there exists I_{2} with left end-point greater than $G\left[a_{o}^{},b_{o}^{}\right]-\epsilon/2$. The I_{1} and I_{2} came from subdivisions $S\left[a_{o}^{},b_{o}^{}\right]$ and $S\left[a_{o}^{},b_{o}^{}\right]$. Then $S\left[a_{o}^{},b_{o}^{}\right]$ = the subdivision, consisting of all end-points of

both original subdivisions so that

$$\mathbf{I}_{3} = \Sigma \left(\mathbf{F} , \mathcal{S}_{\left[\mathbf{a}_{0}^{3} , \mathbf{b}_{0}^{3} \right]}^{3} \right) \subset \left[\Sigma \left(\mathbf{F} , \mathcal{S}_{\left[\mathbf{a}_{0}^{3} , \mathbf{b}_{0}^{3} \right]}^{1} \right) \cap \left[\Sigma \left(\mathbf{F} , \mathcal{S}_{\left[\mathbf{a}_{0}^{3} , \mathbf{b}_{0}^{3} \right]}^{2} \right) \right] = \mathbf{I}_{1} \cap \mathbf{I}_{2}$$

Therefore, $I_3 \subset V_{\epsilon}$. Denote the subdivision $S_{[a_0, b_0]}^3$ as $\{a_0 = x_0, x_1, x_2, \ldots, x_n = b_0\}$. Then,

$$\begin{split} \mathbf{I}_{3} &= \mathbf{F} \left[\mathbf{x}_{0} \; , \; \mathbf{x}_{1} \right] (\mathbf{x}_{1} - \mathbf{x}_{0}) \; + \; \mathbf{F} \left[\mathbf{x}_{1} \; , \; \mathbf{x}_{2} \right] (\mathbf{x}_{2} - \mathbf{x}_{1}) \\ &+ \cdots + \; \mathbf{F} \left[\mathbf{x}_{n-1} \; , \; \mathbf{x}_{n} \right] (\mathbf{x}_{n} - \mathbf{x}_{n-1}) \subset \mathbf{V}_{\epsilon_{1}} \subset \; \mathbf{V}_{\epsilon_{1}} \end{split}$$

where V_{ϵ} is a symmetric neighborhood of I_3 with $\epsilon_1 \leqq \epsilon/2$. Let δ stand for any positive number less than min $(x_1 - x_0^-, x_n^- - x_{n-1}^-)$. By continuity of F, continuity of subtraction, and continuity of multiplication, we can choose δ_0 such that if $\delta < \delta_0^-$, the interval $F\left[x_0^- \pm \delta_0^-, x_1^-\right]\left(x_1^- - (x_0^- \pm \delta)\right)$ differs from $F\left[x_0^-, x_1^-\right]\left(x_1^- - x_0^-\right)$ by an amount less than $\epsilon_1^-/2$. Similarly, $F\left[x_{n-1}^-, x_n^- \pm \delta_0^-\right]\left(x_n^- \pm \delta_0^- - x_{n-1}^-\right)$ differs from $F\left[x_{n-1}^-, x_n^-\right]\left(x_n^- - x_{n-1}^-\right)$ by an amount less than $\epsilon_1^-/2$ and, hence, the expression

$$F\left[x_{0} \pm \delta, x_{1}\right] (x_{1} - x_{0}) + F\left[x_{1}, x_{2}\right] (x_{2} - x_{1}) + \dots + F\left[x_{n-2}, x_{n-1}\right] (x_{n-2} - x_{n-1}) + F\left[x_{n-1}, x_{n} \pm \delta\right] (x_{n} \pm \delta - x_{n-1})$$

differs from the summation I₃, which is identical except for the first and last terms, by an amount less than $\epsilon_1/2 + \epsilon_1/2 = \epsilon_1$. Then if $[a,b] \in N_{\delta_0}[a_o,b_o]$, we have a subdivision

$$\vec{S} = \vec{S}_{[a,b]} = \{x_0 \pm \delta, x_1, x_2, \dots, x_{n-1}, x_n \pm \delta\}$$

such that

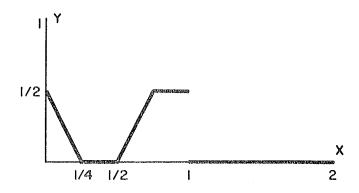
$$\Sigma\left(\mathbf{F}, \overline{\mathcal{S}}_{a, b}\right) \subset \mathbf{V}_{\epsilon_1} \subset \mathbf{V}_{\epsilon}$$

Hence,

$$G\left[a\ ,\ b\right] \ = \ \cap \ \left\{\left(F\ ,\ \mathcal{S}_{\left[a\ ,\ b\right]}\ \right)\right\} \subset \ \bigvee_{\epsilon}$$

and $\, G \,$ is continuous at $\left[{\bf a}_{_{\rm O}} \, , \, {\bf b}_{_{\rm O}} \right]$. This completes the proof.

The following example shows that $A \subset B$ does not imply that $G(A) \subset G(B)$. Define $f: [0, 2] \to B$ as indicated by the graph and $F: \mathcal{J} \to \mathcal{J}$ to be the united extension (Ref. 2, p. 552) of f.



For
$$S_{[0,2]} = \{0, 1/4, 1/2, 1, 2\}$$
 and $B = [0, 2]$,

$$\Sigma\left(F, \mathcal{S}_{\left[0,2\right]}^{1}\right) = F\left[0,1/4\right](1/4) + F\left[1/4,1/2\right](1/4) + F\left[1/2,1\right](1/2) + F\left[1,2\right](1)$$

$$= \left[0,1/2\right](1/4) + \left[0,0\right](1/4) + \left[0,1/2\right](1/2) + \left[1/2,1/2\right](1)$$

$$= \left[0,1/8\right] + \left[0,0\right] + \left[0,1/4\right] + \left[1/2,1/2\right]$$

$$= \left[1/2,7/8\right]$$

Now for
$$A = [1/4, 1/2]$$
, $A \subseteq B$. But for $S_{[1/4, 1/2]} = \{1/4, 1/2\}$,

$$\Sigma\left(\mathbf{F},\mathcal{S}_{\mathbf{A}}\right) = \mathbf{F}\left[1/4,1/2\right]\left(1/2-1/4\right) = \left[0,0\right]\left(1/4\right) = \left[0,0\right]$$

But every further subdivision of B will include the summation over $\begin{bmatrix} 1,2 \end{bmatrix}$ and hence the summand $\begin{bmatrix} 1/2,1/2 \end{bmatrix}$, and hence have left end-point $\geq 1/2$. Therefore, $G(B) = \begin{bmatrix} 1/2+r,k \end{bmatrix}$ where $r \geq 0$, and $G(A) = \begin{bmatrix} 0,0 \end{bmatrix}$ is not contained in G(B).

However, if for every $X \subset A$ we have $F_1(X) \subset F_2(X)$, then

$$\int_{A} F_1 \subset \int_{A} F_2$$

Section 3 DEPENDENCE ON DEGENERATE INTERVALS

Theorem 2. Let F_2 and F_1 be continuous functions from $\mathcal J$ to $\mathcal J$ such that $M\subset N$ implies $F_i(M)\subset F_i(N)$, (i=1,2). Let $G_2=\int F_2$ and $G_1=\int F_1$ and $F\left[x\,,\,x\right]=F_1\left[x\,,\,x\right]$ for all $x\in A$. Then $G_2(A)=G_1(A)$.

<u>Proof</u>: It is sufficient to show that every neighborhood of $G_2(A)$ contains $G_1(A)$ and conversely. As the arguments are identical, only one of these will be shown.

<u>Lemma 1</u>. If $\{I_{\alpha}\}$ is a descending collection of closed intervals (i.e., for any two of them there is a third one contained in their intersection) and $I_{\alpha} = \bigcap \{I_{\alpha}\}$, then every neighborhood of I_{α} contains some $I_{\alpha} \in \{I_{\alpha}\}$.

Proof of Lemma 1: Let I_0 be contained in $N_{\epsilon} = N_{\epsilon}(I_0)$, $I_0 = [a, b]$. Assume that every I_{α} has left end-point $a_{\alpha} \leq a_0 - \epsilon$. Then $\bigcap_{\alpha} \{I_{\alpha}\}$ has left end point $\leq a_0 - \epsilon$; therefore, $a_0 \leq a_0 - \epsilon$. This is a contradiction and the assumption is false. Hence, there exists I_{α_1} with left end-point $a_{\alpha_1} > a_0 - \epsilon$. Similarly, there exists I_{α_2} with right end-point $b_{\alpha_2} < b_0 + \epsilon$. Hence, $[a_{\alpha_1}, b_{\alpha_2}] \subset N_{\epsilon}$. But in this descending collection, there exists α_3 such that

$$\mathbf{I}_{\alpha_3} \subset \ \mathbf{I}_{\alpha_1} \cap \ \mathbf{I}_{\alpha_2} \subset \left[\mathbf{a}_{\alpha_1} \text{ , } \mathbf{b}_{\alpha_2} \right] \subset \mathbf{N}_{\epsilon}$$

Lemma 2. Let \mathcal{S}_A be a subdivision of A = [a, b], and $\overline{\mathcal{S}}_A$ a subdivision of A including all the points of \mathcal{S}_A and more. Then $\Sigma\left(F_2, \overline{\mathcal{S}}_A\right) \subset \Sigma\left(F_2, \mathcal{S}_A\right)$.

Proof: Let

$$S_A = \{a = a_0, a_1, \dots, a_n = b\}$$

and let

$$S_{\overline{A}} = \{ a = a_0, a_0^1, \dots, a_0^{m_0}, a_1, a_1^1, \dots, a_1^{m_0}, a_2, \dots a_3, \dots, a_n = b \}$$

Then

$$\Sigma(F_{2}, \mathcal{S}_{A}) = F_{2} \left[a_{0}, a_{0}^{1} \right] (a_{0}^{1} - a_{0}) + \dots + F_{2} \left[a_{0}^{m_{0}}, a_{1} \right] (a_{1}^{1} - a_{0}^{m_{0}})$$

$$+ F_{2} \left[a_{1}, a_{1}^{1} \right] (a_{1}^{1} - a_{1}) + \dots + F_{2} \left[a_{1}^{m_{1}}, a_{2} \right] (a_{2}^{1} - a_{1}^{m_{1}})$$

$$+ \dots$$

$$+ F_{2} \left[a_{n-1}, a_{n-1}^{1} \right] (a_{n-1}^{1} - a_{n-1}) + \dots + F_{2} \left[a_{n-1}^{m_{n-1}}, a_{n} \right] (a_{m}^{1} - a_{m-1}^{m_{n-1}})$$

Denote the lines in the above summation as S_0^1 , S_1^2 , \cdots , S_{m-1}^m respectively. Now,

$$\Sigma(F_2, S_A) = F_2[a_0, a_1](a_1 - a_0) + \cdots + F_2[a_{n-1}, a_n](a_n - a_{n-1})$$

Since $I_n \subset J_n$ implies that $\Sigma I_n \subset \Sigma J_n$, it will be sufficient to show that

$$S_0^1 \subset F_2[a_0, a_1] (a_1 - a_0), S_1^2 \subset F_2[a_1, a_2] (a_2 - a_1),$$

$$\dots S_{n-1}^n \subset F_2[a_{n-1}, a_n] (a_n - a_{n-1})$$

Consider the first term, S_2^1 . We have

$$S_{0}^{1} = F_{2} \left[a_{0}, a_{0}^{1} \right] (a_{0}^{1} - a_{0}) + \dots + F_{2} \left[a_{0}^{m_{0}}, a_{1} \right] (a_{1} - a_{0}^{m_{0}})$$

$$\subset F_{2} \left[a_{0}, a_{1} \right] (a_{0}^{1} - a_{0}) + \dots + F_{2} \left[a_{0}, a_{1} \right] (a_{1} - a_{0}^{m_{0}})$$

$$= F_{2} \left[a_{0}, a_{1} \right] (-a_{0} + a_{0}^{1} - a_{0}^{1} + a_{0}^{2} - a_{0}^{2} + \dots + a_{1})$$

$$= F_{2} \left[a_{0}, a_{1} \right] (a_{1} - a_{0})$$

The same argument holds for the general term and the lemma is proved.

Lemma 3. The term $\{\Sigma(F, \mathcal{S}_A)\}$ is a descending collection of closed intervals.

 $\begin{array}{lll} \underline{\operatorname{Proof}}\colon \operatorname{Let} \ \Sigma\left(F,\,\mathcal{S}_{A}^{\,1}\right) \ \operatorname{and} \ \Sigma\left(F,\,\mathcal{S}_{A}^{\,2}\right) \ \operatorname{be\ elements\ of\ the\ collection}. \ \operatorname{Denote\ by} \\ \underline{\mathcal{S}_{A}^{\,3}} \ \operatorname{the\ collection\ of\ points\ in\ both} \ \underline{\mathcal{S}_{A}^{\,1}} \ \operatorname{and} \ \underline{\mathcal{S}_{A}^{\,2}} \ . \ \operatorname{By\ lemma\ 2}, \ \Sigma\left(F,\,\mathcal{S}_{A}^{\,3}\right) \subset \\ \Sigma\left(F,\,\mathcal{S}_{A}^{\,1}\right) \ \operatorname{and} \ \Sigma\left(F,\,\mathcal{S}_{A}^{\,3}\right) \subset \Sigma\left(F,\,\mathcal{S}_{A}^{\,2}\right) \ . \ \operatorname{Hence} \ \Sigma\left(F,\,\mathcal{S}_{A}^{\,3}\right) \ \operatorname{is\ contained\ in\ their\ intersection}. \end{array}$

 an open set $\overline{N}_{\varepsilon_0}$, therefore there exists and $\varepsilon > 0$ such that $\overline{N}_{\varepsilon} \Sigma (F_2, S_A^0) \subset \overline{N}_{\varepsilon_0}$ Denote the subdivision $S_A^0 = \{a = x_0, x_1, x_2, \dots, x_n = b\}$. Then

$$\begin{split} \overline{N}_{\epsilon_{_{\scriptscriptstyle{O}}}} &= N_{\epsilon_{_{\scriptscriptstyle{O}}}}\!\!\left(G(A)\right) \supset \overline{N}_{\epsilon} \left[F_{_{\scriptscriptstyle{2}}}\left[x_{_{\scriptscriptstyle{O}}}\,,\,x_{_{\scriptscriptstyle{1}}}\right](x_{_{\scriptscriptstyle{1}}}-x_{_{\scriptscriptstyle{O}}})^{+}\cdots\right. \\ &+ F_{_{\scriptscriptstyle{2}}}\left[x_{_{\scriptscriptstyle{m-1}}}\,,\,x_{_{\scriptscriptstyle{m}}}\right](x_{_{\scriptscriptstyle{m}}}-x_{_{\scriptscriptstyle{m-1}}})\right] &= \overline{N}_{\epsilon}\!\!\left[\Sigma\!\left(F_{_{\scriptscriptstyle{2}}}\,,\,\mathcal{S}_{A}^{\scriptscriptstyle{O}}\right)\right] \end{split}$$

Let $N^o = N^o_{\epsilon/n}$ be an ϵ/n neighborhood of the interval $F_2[x_0, x_1](x_1 - x_0)$. Assume that there is no subdivision $S[x_0, x_1]$ of $[x_0, x_1]$ such that $\Sigma(F_1, S[x_0, x_1]) \subset N^o$.

Denote

by \mathcal{S}_1 the subdivision $\{\mathbf{x}_0, \, \mathbf{x}_1\}$ of $\left[\mathbf{x}_0, \, \mathbf{x}_1\right]$,

by S_2 the subdivision $\{x_0 = y_2^0, y_2^1, y_2^2 = x_1\}$ into 2 equal parts,

by S_3 the subdivision $\{x_0 = y_3^0, y_3^1, y_3^2, y_3^2 = x_1\}$ into 3 equal parts,

... by S_p the subdivision $\{x_0 = y_p^0, y_p^1, \dots, y_p^p = x_1\}$ into p equal parts, etc.

Then for each p, $\Sigma\left(F_1,\mathcal{S}_p\right)\not\subset N^O$. Denote the right end-points of $F_2\left[x_0,\,x_1\right](x_1-x_0)+\varepsilon/n$ and of $\Sigma\left(F_1,\mathcal{S}_p\right)$ by r_0 and r_p respectively, for p>0. For a set A we will also use the notation r(A) and $\ell(A)$ for the right and left end-points of A. Either there are infinitely many p for which $r_p\geqq r_0$, or else a similar statement holds for left end-points. The former case will be treated here. In this case there is a subsequence $\{\mathcal{S}_m\}\subset\{\mathcal{S}_p\}$ such that, for all m, $r_m\geqq r_0$. In the summation $\Sigma\left(F_1,\,\mathcal{S}_m\right)$ there are m intervals $\left[y_m^i\,,\,y_m^{i+1}\right]$ all of the same length. Denote by $\left[a_m,\,b_m\right]$ one of these for which the right end-point of $F_2\left[a_m,\,b_m\right]$ is maximum.

Then

$$\begin{split} \mathbf{r}_{o} & \leq & \mathbf{r} \left[\left[(\mathbf{F}_{1} , \mathcal{S}_{m}) \right] = \mathbf{r} \left(\mathbf{F}_{1} \left[\mathbf{x}_{o} , \mathbf{y}_{m}^{1} \right] \left(\mathbf{y}_{m}^{1} - \mathbf{x}_{o} \right) + \left[\mathbf{F}_{1} \left[\mathbf{y}_{m}^{1} , \mathbf{y}_{m}^{2} \right] \left(\mathbf{y}_{m}^{2} - \mathbf{y}_{m}^{1} \right) \right) \\ & + \cdots + \left[\mathbf{F}_{1} \left[\mathbf{y}_{m}^{m-1} , \mathbf{y}_{m}^{m} = \mathbf{x}_{1} \right] \left(\mathbf{y}_{m}^{m} - \mathbf{y}_{m}^{m-1} \right) \right) \\ & \leq & \mathbf{r} \left(\mathbf{F}_{1} \left[\mathbf{a}_{m} , \mathbf{b}_{m} \right] \left(\mathbf{y}_{m}^{1} - \mathbf{x}_{o} \right) + \left[\mathbf{F}_{1} \left[\mathbf{a}_{m} , \mathbf{b}_{m} \right] \left(\mathbf{y}_{m}^{2} - \mathbf{y}_{m}^{1} \right) \right) \\ & + \cdots + \left[\mathbf{F}_{1} \left[\mathbf{a}_{m} , \mathbf{b}_{m} \right] \left(\mathbf{y}_{m}^{1} - \mathbf{x}_{o} + \mathbf{y}_{m}^{2} - \mathbf{y}_{m}^{1} + \cdots + \mathbf{x}_{1} - \mathbf{y}_{m}^{m-1} \right) \right) \\ & = & \mathbf{r} \left(\mathbf{F}_{1} \left[\mathbf{a}_{m} , \mathbf{b}_{m} \right] \left(\mathbf{x}_{1} - \mathbf{x}_{o} \right) \right) \end{split}$$

Now some subsequence of $\left\{ \begin{bmatrix} a_m & b_m \end{bmatrix} \right\}$ converges to a point $\begin{bmatrix} \bar{x} & \bar{x} \end{bmatrix}$ with $x_0 \le \bar{x} \le x_1$. We will retain the notation so as to write $\left\{ \begin{bmatrix} a_m & b_m \end{bmatrix} \right\} \rightarrow \begin{bmatrix} \bar{x} & \bar{x} \end{bmatrix}$ as $m \to \infty$. Since F_1 is continuous, $\left\{ F_1 \begin{bmatrix} a_m & b_m \end{bmatrix} \right\}$ converges to $F_1 \begin{bmatrix} \bar{x} & \bar{x} \end{bmatrix}$. It follows that $\left\{ r F_1 \begin{bmatrix} a_m & b_m \end{bmatrix} (x_1 - x_0) \right\}$, since this is still a continuous function of $\begin{bmatrix} a_m & b_m \end{bmatrix}$, converges to

$$r \ F_1 \ [\bar{x} \ , \ \bar{x}] (x_1 - x_0) = r \ F_2 \ [\bar{x} \ , \ \bar{x}] (x_1 - x_0)$$

$$\leq r \ F_2 \ [x_0 \ , x_1] (x_1 - x_0) = r_0 - \epsilon/n$$

But every $r F_1 [a_m, b_m] (x_1 - x_0) \ge r_0$; therefore,

$$\lim_{n\to\infty} F_1 \left[a_m , b_m \right] (x_1 - x_0) = r_1 \ge r_0$$

We now have

$$r_{0} \leq r_{1} = \lim_{m \to \infty} r F_{1} [a_{m}, b_{m}] (x_{1} - x_{0}) \leq r_{0} - \epsilon/m$$

This is a contradiction. Hence our assumption was false and there exists a subdivision \mathcal{S}^1 of $[x_0^0, x_1^0]$ such that

$$\Sigma(F_1, S^1) \subset N_{\epsilon/n} F_1[x_0, x_1](x_1, x_0)$$

Similarly, there is a subdivision \mathcal{S}^i of $\left[\mathbf{x}_i^{}$, $\mathbf{x}_{i+1}^{}\right]$ such that

$$\Sigma(F_1, S^i) \subset N_{\epsilon/n} F_1[x_{i-1}, x_i](x_i - x_{i-1})$$

for each $\ i=1,\,2,\,\cdots,\,n$. The set $\overline{\mathcal{S}}_A$ consisting of all the points in the union of the divisions

$$\mathcal{S}^1$$
 of $[x_0, x_1]$, \mathcal{S}^2 of $[x_1, x_2]$, ..., \mathcal{S}^m of $[x_{n-1}, x_n]$

is a subdivision of $\begin{bmatrix} x_0, x_n \end{bmatrix} = \begin{bmatrix} a, b \end{bmatrix} = A$, and

$$\begin{split} \mathbf{G}_{1}(\mathbf{A}) &= \mathbf{G}_{1}\left[\mathbf{a} \;,\; \mathbf{b}\right] \subset \boldsymbol{\Sigma}(\mathbf{F}_{1} \;,\; \boldsymbol{\mathcal{S}}_{\mathbf{A}}) \\ &= \sum_{i=1}^{n} \left(\boldsymbol{\Sigma}\left(\mathbf{F}_{1} \;,\; \boldsymbol{\mathcal{S}}^{i}\right)\right) \subset \sum_{i=1}^{n} \; \mathbf{N}_{\epsilon \; / \mathbf{N}}\left[\boldsymbol{\Sigma}(\mathbf{F} \;,\; \boldsymbol{\mathcal{S}}^{i})\right] \subset \mathbf{N}_{\epsilon} \left[\sum_{i=1}^{n} \left(\boldsymbol{\Sigma}(\mathbf{F} \;,\; \boldsymbol{\mathcal{S}}^{i})\right)\right] \\ &= \; \mathbf{N}_{\epsilon} \left[\boldsymbol{\Sigma}(\mathbf{F} \;,\; \boldsymbol{\mathcal{S}}_{\mathbf{A}})\right] \subset \; \mathbf{N}_{\epsilon} \left[\boldsymbol{\Sigma}\left(\mathbf{F} \;,\; \boldsymbol{\mathcal{S}}_{\mathbf{A}}^{o}\right)\right] = \; \overline{\mathbf{N}}_{\epsilon} \; = \; \overline{\mathbf{N}}_{\epsilon_{\mathbf{O}}} \end{split}$$

It follows immediately from theorem 2 that if F_1 and F_2 are continuous functions from J to J such that $M \subset N$ implies $F_i(M) \subset F_i(N)$, (i=1, 2) and $F_1\left[x \ , \ x\right] = F_2\left[x \ , \ x\right]$ for all $x \in A$, then for every interval $A' \subset A$ we have $G_1(A') = G_2(A')$ with $G_1(A') = \int_A F_1$ and $G_2(A') = \int_A F_2$. Accordingly, we have the following converse theorem.

Theorem 3. Suppose F_1 and F_2 are continuous functions from $\mathcal J$ to $\mathcal J$ such that $M\subset N$ implies $F_i(M)\subset F_i(N)$ (i=1,2). Let $G_1=\mathcal J F_1$ and $G_2=\mathcal J F_2$. If for every interval $A'\subset A$ we have $G_1(A')=G_2(A')$ then $F_1\left[x\,,\,x\right]=F_2\left[x\,,\,x\right]$ for every $x\in A$.

<u>Proof:</u> Suppose the conclusion is false; i.e., that for some $x' \in A$ we have $F_1[x', x'] \neq F_2[x', x']$. It suffices to show that for some $A' \subseteq A$ such that $x' \in A'$ we have $G_1(A') \neq G_2(A')$. Denote by $r F_1(X)$ right end-point of $F_1(X)$ (i = 1, 2). Without loss of generality we may assume that $r F_1[x', x'] \leq r F_2[x', x']$. The functions F_1 , F_2 , are continuous; hence, for some $A' \subseteq A$ such that $x' \in A'$, we have $A'' \subseteq A' \Rightarrow r F_1(A'') < r F_2(A'')$.

We assert that

$$r G_1(A') = r \int_{A'} F_1 < r G_2(A') = r \int_{A'} F_2$$

Otherwise (if $r G_1(A') \ge r G_2(A')$), for any $\epsilon > 0$ there is a subdivision \mathcal{S}_2 of A' such that $r G_2(A') > r \sum_{i=0}^{\infty} (F_2, \mathcal{S}_2) - \epsilon$ and a subdivision \mathcal{S}_1 of A' such that $r G_1(A') \le r \sum_{i=0}^{\infty} (F_1, \mathcal{S}_1)$. Then let \mathcal{S}_3 be the subdivision of A' consisting of the points $x_0 < x_1 < \cdots = x_n$ in either \mathcal{S}_1 or \mathcal{S}_2 and we have $r \sum_{i=0}^{\infty} (F_1, \mathcal{S}_3) > r \sum_{i=0}^{\infty} (F_2, \mathcal{S}_3) - \epsilon$. But this inequality means that

$$r \left\{ F_{1} \left[x_{0}, x_{1} \right] (x_{1} - x_{0}) + \dots + F_{1} \left[x_{n-1}, x_{n} \right] (x_{n} - x_{m-1}) \right\}$$

$$> r \left\{ F_{2} \left[x_{0}, x_{1} \right] (x_{1} - x_{0}) + \dots + F_{2} \left[x_{n-1}, x_{n} \right] (x_{n} - x_{n-1}) \right\} - \epsilon$$

It follows from the above inequality that

$$0 \geq (x_{1} - x_{0}) \left(r F_{2} \left[x_{0}, x_{1} \right] - r F_{1} \left[x_{0}, x_{1} \right] \right)$$

$$+ \dots + (x_{n} - x_{n-1}) \left(r F_{2} \left[x_{n-1}, x_{n} \right] - r F_{1} \left[x_{n-1}, x_{m} \right] \right)$$

since ϵ is arbitrary. However, $\left[x_{i-1}^{-1}, x_{i}^{-1}\right] \subset A'$ for $i=1,\cdots,n$, so $r \ F_{2}\left[x_{i-1}^{-1}, x_{i}^{-1}\right] - r \ F_{1}\left[x_{i-1}^{-1}, x_{i}^{-1}\right] > 0$ which is a contradiction. Therefore, $r \ G_{1}(A') < r \ G_{2}(A')$ and the proof is complete.

Theorem 2 and theorem 3 may be combined into the following statement:

Theorem (2-3): Let F_1 , F_2 be continuous functions from $\mathcal I$ to $\mathcal I$ such that $M\subset N$ implies $F_1(M)\subset F_1(N)$ (i = 1,2). Let $G_1=\mathcal IF_1$ and $G_2=\mathcal IF_2$. Then the following are equivalent:

(1)
$$F_1[x, x] = F_2[x, x]$$
 for all $x \in A$

(2)
$$G_1(A_1) = G_2(A_1)$$
 for all $A_1 \subseteq A$

Remark: Theorem 2 indicates that the integral is heavily dependent on the behavior of F on the special intervals [x, x], and little dependent on the character of F on long intervals. It suggests that a related integral defined only in terms of intervals [x, x] might be sought.

Section 4

REFERENCES

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Appendix A RELATION TO ORDINARY INTEGRATION

This appendix deals with the question raised in the remark following theorem 2.

Inasmuch as $\Sigma(F,\mathcal{S})$ is a descending collection of intervals, the left end-points form a nondecreasing sequence and, hence, the left end-point of the intersection $\{\Sigma(F,\mathcal{S})\}=f_AF$ is the limit of the left end-points of the $\{\Sigma(F,\mathcal{S})\}$. In fact, if we start with $S_1=\{a,b\}$ and continue subdividing so that S_n consists of n equal parts, then the left end-point of f_AF is $\lim_{n\to\infty}\pi_1$ $\Sigma(F,\mathcal{S}_n)$, where π_1 is defined by $\pi_1(K)=\{b\}$ the left end-point of f_AF is f_AF by $f_A(F)=\{b\}$ a function f_AF by $f_A(F)=\{b\}$ where f_AF is the largest interval in f_AF ; i.e., f_AF is the set of all subintervals of f_AF or Define similarly f_AF and f_AF or right end-points. Then we have

Theorem 4:

$$f_{a,b}$$
 $F = \begin{bmatrix} b \\ f \\ f \end{bmatrix} (x) dx , \int_{a}^{b} f_{r}(x) dx$

Proof:

$$\begin{split} \int_{\begin{bmatrix} \mathbf{a} &, \mathbf{b} \end{bmatrix}} \mathbf{F} &= \bigcap_{\mathbf{n}} \left\{ \Sigma(\mathbf{F} \,,\, \boldsymbol{\mathcal{S}}_{\mathbf{n}}) \right\} \\ &= \begin{bmatrix} \lim_{\mathbf{n} \to \infty} \Sigma \, \pi_{\mathbf{1}} \, \mathbf{F} \left[\mathbf{x}_{\mathbf{i}} \,,\, \mathbf{x}_{\mathbf{i}+1} \right] \left(\mathbf{x}_{\mathbf{i}+1} - \mathbf{x}_{\mathbf{i}} \right) \,, \\ \lim_{\mathbf{n} \to \infty} \Sigma \, \pi_{\mathbf{2}} \, \mathbf{F} \left[\mathbf{x}_{\mathbf{i}} \,,\, \mathbf{x}_{\mathbf{i}+1} \right] \left(\mathbf{x}_{\mathbf{i}+1} - \mathbf{x}_{\mathbf{i}} \right) \right] \\ &= \begin{bmatrix} \lim_{\mathbf{n} \to \infty} \sum_{\mathbf{i}=1}^{\mathbf{n}} \pi_{\mathbf{1}} \, \mathbf{F} \left[\mathbf{x}_{\mathbf{i}} \,,\, \mathbf{x}_{\mathbf{i}+1} \right] \left(\frac{1}{\mathbf{n}} \right), \, \sum_{\mathbf{i}=1}^{\mathbf{n}} \pi_{\mathbf{2}} \, \mathbf{F} \left[\mathbf{x}_{\mathbf{i}} \,,\, \mathbf{x}_{\mathbf{i}+1} \right] \left(\frac{1}{\mathbf{n}} \right) \right] \\ &= \begin{bmatrix} \lim_{\mathbf{n} \to \infty} \left(\frac{1}{\mathbf{n}} \right) \sum_{\mathbf{i}=1}^{\mathbf{n}} \pi_{\mathbf{1}} \, \mathbf{F} \left[\mathbf{x}_{\mathbf{i}} \,,\, \mathbf{x}_{\mathbf{i}+1} \right], \, \lim_{\mathbf{n} \to \infty} \left(\frac{1}{\mathbf{n}} \right) \sum_{\mathbf{i}=1}^{\mathbf{n}} \pi_{\mathbf{2}} \, \mathbf{F} \left[\mathbf{x}_{\mathbf{i}} \,,\, \mathbf{x}_{\mathbf{i}+1} \right] \right] \end{split}$$

Then

$$\int_{a}^{b} f_{\ell}(x) dx = \lim_{n \to \infty} \sum_{i=1}^{n} (f_{\ell}(x_{i})) (x_{i+1} - x_{i}) = \lim_{n \to \infty} \sum_{i=1}^{n} \frac{1}{n} f_{\ell}(x_{i})$$

and

$$\int_{a}^{b} f_{\mathbf{r}}(\mathbf{x}) d\mathbf{x} = \lim_{n \to \infty} \sum_{i=1}^{n} \frac{1}{n} f_{\mathbf{r}}(\mathbf{x}_{i})$$

Hence it is sufficient to prove that $\lim_{n\to\infty} \frac{1}{n} \sum_{i=1}^n \pi_i \ F[x_i, x_{i+1}]$ equals $\lim_{n\to\infty} \sum_{i=1}^n \frac{1}{n} \ f_\ell(x_i)$ and the similar result for π_2 F and f_r . By definition of f_ℓ

$$\lim_{n \to \infty} \sum_{i=1}^{n} \frac{1}{n} f_{\ell}(x_i) = \lim_{n \to \infty} \sum_{i=1}^{n} \frac{1}{n} \pi_1 F[x_i, x_i]$$

and, hence, what we need to prove is that

$$\lim_{n \to \infty} \sum_{i=1}^{n} \frac{1}{n} \pi_{1} F \left[x_{i}, x_{i}\right] = \lim_{n \to \infty} \sum_{i=1}^{n} \frac{1}{n} \pi_{1} F \left[x_{i}, x_{i+1}\right]$$

Since

$$F[x_i, x_i] \subset F[x_i, x_{i+1}]$$

then

$$\pi_1 F[x_i, x_i] \ge \pi_1 F[x_i, x_{i+1}]$$

Hence, it is sufficient to prove that for every positive number ϵ there exists n_0 such that $n > n_0$ implies

$$\left(\sum_{i=1}^{n} \frac{1}{n} \pi_{1} F \left[x_{i}, x_{i}\right] - \sum_{i=1}^{n} \frac{1}{n} \pi_{1} F \left[x_{i}, x_{i+1}\right]\right) < \epsilon$$

Then

$$\sum_{i=1}^{n} \frac{1}{n} \pi_{1} F \left[x_{i}, x_{i}\right] - \sum_{i=1}^{n} \frac{1}{n} \pi_{1} F \left[x_{i}, x_{i+1}\right]$$

$$= \frac{1}{n} \left(\sum_{i=1}^{n} \pi_{1} F \left[x_{i}, x_{i}\right] - \sum_{i=1}^{n} \pi_{1} F \left[x_{i}, x_{i+1}\right]\right)$$

$$= \frac{1}{n} \sum_{i=1}^{n} \left(\pi_{1} F \left[x_{i}, x_{i}\right] - \pi_{i} F \left[x_{i}, x_{i+1}\right]\right)$$

But π_1 F uniformly continuous implies that there exists δ_ϵ such that $|\mathbf{x}_i - \mathbf{x}_{i+1}| < \delta_\epsilon$ implies that

$$\left(\pi_{1} F \left[x_{i}, x_{i}\right] - \pi_{1} F \left[x_{i}, x_{i+1}\right]\right) < \epsilon$$

There exists n such that n > n implies $1/n < \delta_{\epsilon}$. Then n > n implies

$$|\mathbf{x_i} - \mathbf{x_{i+1}}| < \delta_{\epsilon}$$
 and $\pi_1 \mathbf{F} [\mathbf{x_i}, \mathbf{x_i}] - \pi_1 \mathbf{F} [\mathbf{x_i}, \mathbf{x_{i+1}}] < \epsilon$

Then $n > n_0$ implies

$$1/n = |x_i - x_{i+1}| < \delta_{\epsilon} \text{ and } \pi_1 F[x_i, x_i] - \pi_1 F[x_i, x_{i+1}] < \epsilon$$

Hence,

$$n > n_{o} \Rightarrow \frac{1}{n} \left[\sum_{i=1}^{n} \left(\pi_{1} F \left[x_{i}, x_{i} \right] - \pi_{1} F \left[x_{i}, x_{i+1} \right] \right) \right] < \frac{1}{n} \left[\sum_{i=1}^{n} \epsilon \right] = \frac{1}{n} (n \epsilon) = \epsilon$$

A similar statement holds for right end-points and the theorem is proved.

It follows trivially that if F[x, x] is real for all x, the left and right end-points of F[x, x] are identical and, hence,

$$\int_{a, b} F = \begin{bmatrix} \int_{a}^{b} f_{\ell}(x) dx, & \int_{a}^{b} f_{\ell}(x) dx \end{bmatrix}$$

i.e., $\int_{a, b} F$ reduces to ordinary integration.

Theorem 4 suggests a more general definition for fF may be feasible—namely the right side of the equality in theorem 4. This conclusion could lead to a deletion of the condition $A \subseteq B \Rightarrow F(A) \subseteq F(B)$. A definition of a derivative of F as the anti-integral involving f_{ℓ} and f_{r} may also prove interesting.